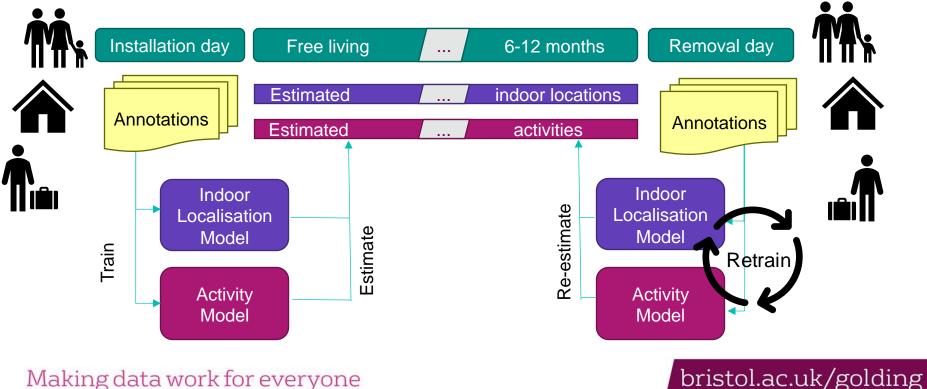
Data integration and Learning

With thanks to: Peter Flach, Raul Santos-Rodriguez, Alessandro Masullo Miquel Perello-Nieto, Haixia Bi, Emma Tonkin, Taku Yamagata In This Section

- 1. Installation, annotation and training overview
- 2. Indoor localisation
- 3. Activity recognition
- 4. Case study
- 5. Other examples

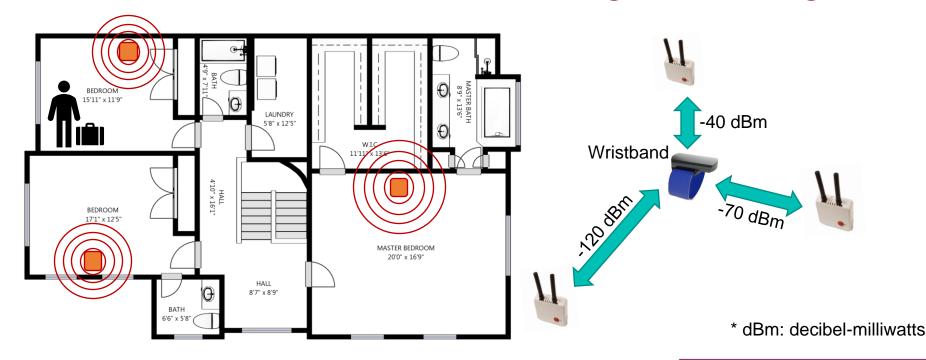


Installation and annotation process



9

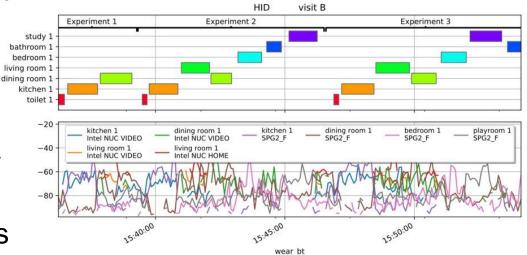
Localisation from Received Signal Strength



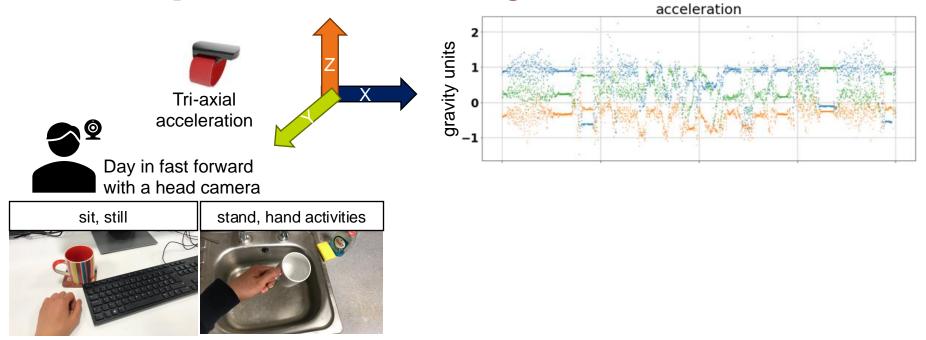
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Example of location annotations

- At least 2 experiments per visit
- Visit every room and annotate the location
- We record the Received Signal Strength Intensity
- Train model and use to estimate indoor locations

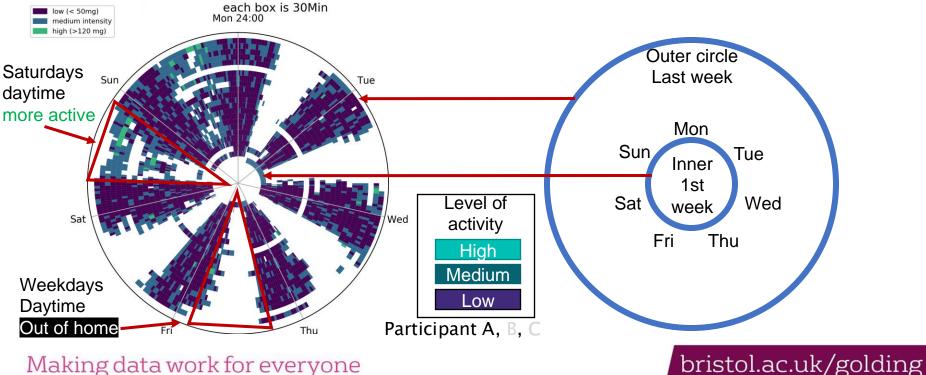


Activity levels and recognition

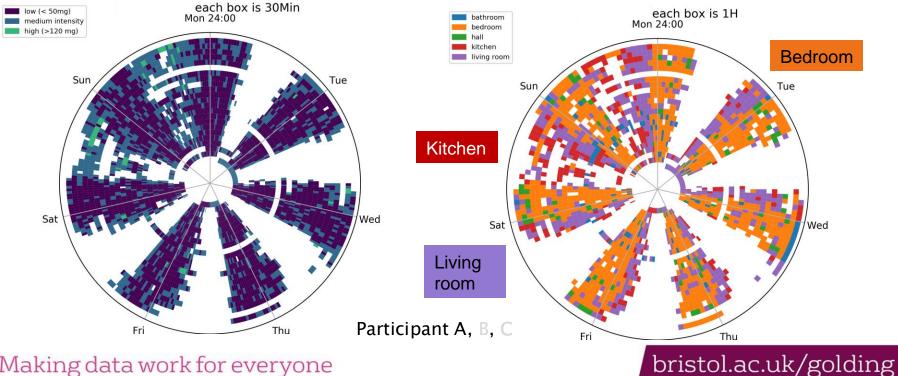


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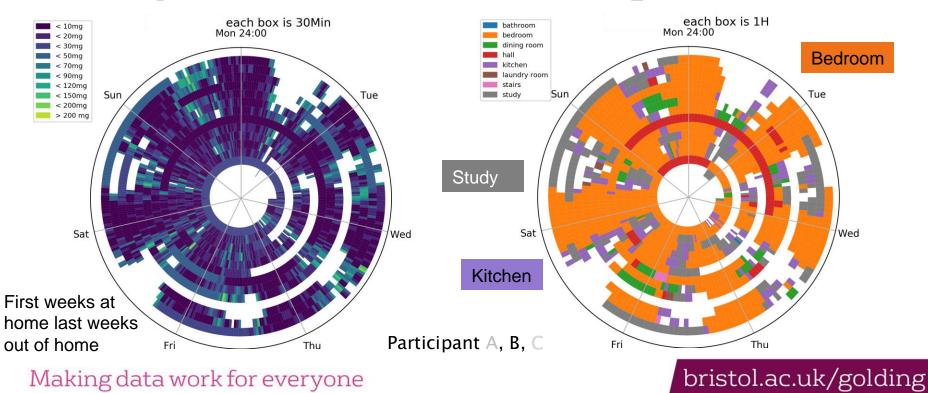
Activity levels for the full period



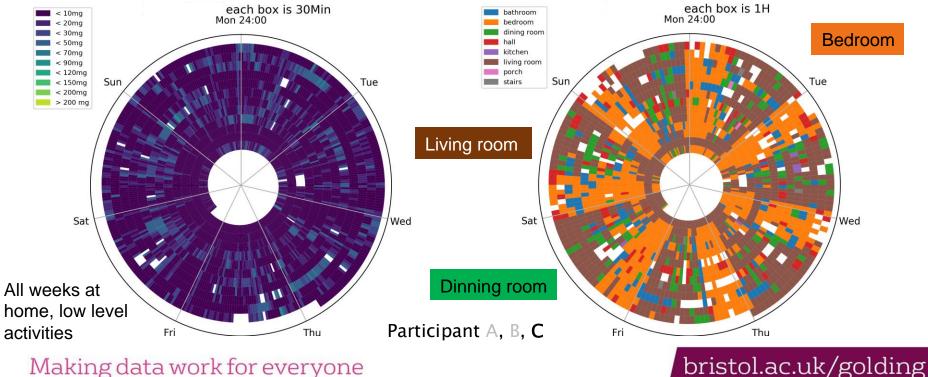
Activity levels and localisation predictions:



Activity levels and localisation predictions:

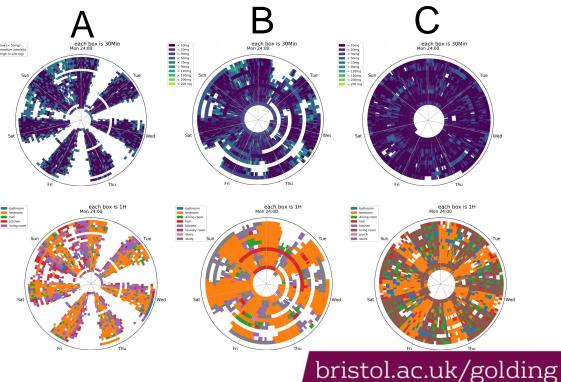


Activity levels and localisation predictions:

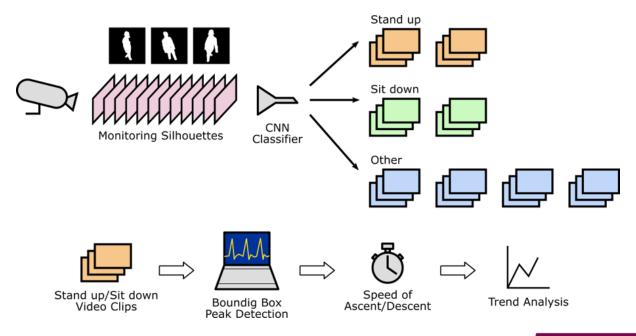


Activity and Locations overview

- A is a participant from the control group
- B and C are recovering from a hip replacement surgery
- B and C spend more time at home, and are generally less active



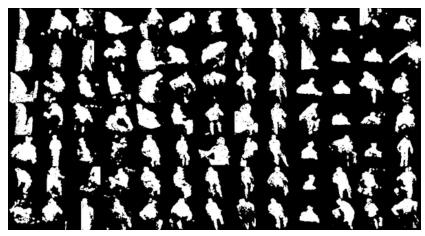
Sit to Stand as a surrogate of recovery



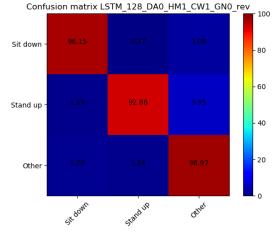
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Sit to Stand Detector (Classifier)

- Using MuViLab, we have annotated 4 months of video data for STS transitions.
- Using a convolutional neural network we were able to achieve >90% accuracy in classifying video sequences:

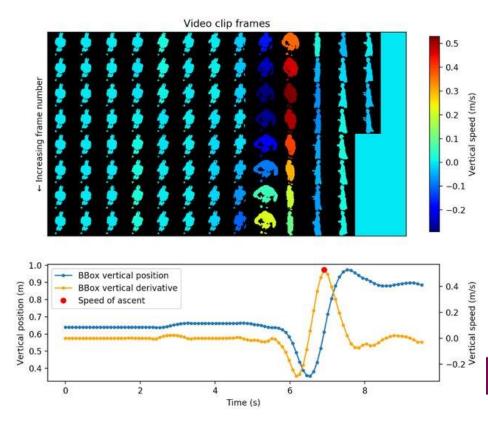


Examples of 4 seconds video sequences detected as stand up transitions.



Bounding box peak detection

- The figure shows an example of analysis of sit-to-stand transition using silhouettes.
- On top are the frames of the video sequence of a person standing up, on the bottom the analysis derived from their movement.
- The red dot shows the speed of ascent, i.e. the maximum transfer velocity from sitting to standing position.

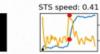


Several Examples of Sit to Stand Speed













STS speed: 0.28

Bbox y coord.

Debyative

0.2

0.0

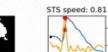
0.2

0.0

0.25

0.00





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0.5

0.0







STS speed: 0.55











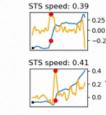














-0.2























STS speed: 0.80

STS speed: 0.34

STS speed: 0.41

STS speed: 0.43

STS speed: 0.55

0.25

0.00

0.2

0.0

0.25

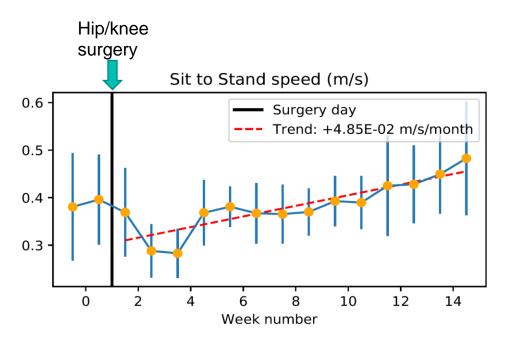
0.00

0.5



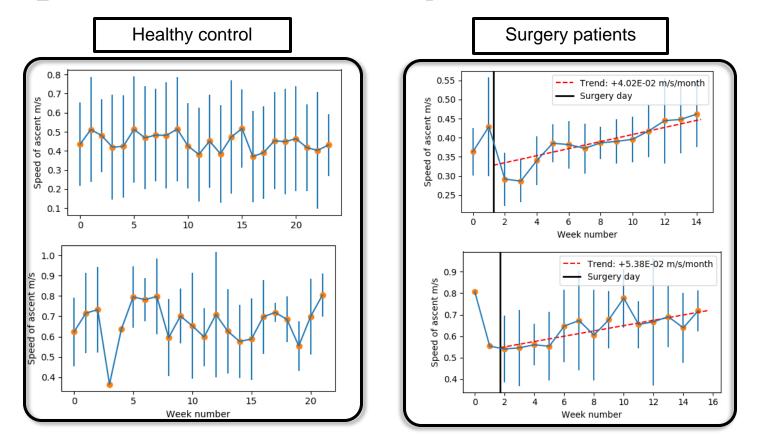
What Does This Look Like for a Patient?

- Recover from hip/knee replacement
- Sit to Stand speed decreases abruptly after surgery
- After that, the speed gradually increases

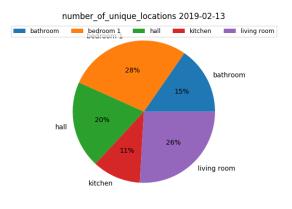


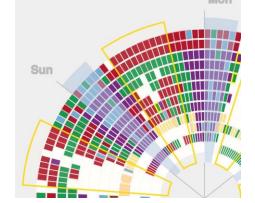
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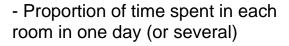
Comparison With Healthy Control



Other examples of available data

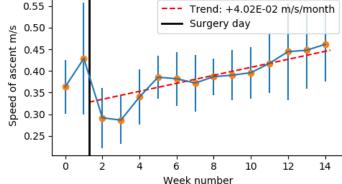






- Or Number of transitions between rooms

- Actigraphy for the study of sleep and circadian rhythms. Cut out of a circular plot showing the 10 most active hours (yellow box) and 5 less active (light blue) [2] Making data work for everyone



- Speed of ascent from sit to stand for a patient recovering from a hip replacement [3]

References

- [1] M. Holmes, H. Song, E. Tonkin, M. P. Nieto, S. Grant, and P. Flach, "Analysis of patient domestic activity in recovery from hip or knee replacement surgery: Modelling wrist-worn wearable RSSI and accelerometer data in the wild," in CEUR Workshop Proceedings, 2018, vol. 2148.
- [2] M. Holmes, M. P. Nieto, H. Song, E. Tonkin, S. Grant, and P. Flach, "Modelling Patient Behaviour Using IoT Sensor Data: a Case Study to Evaluate Techniques for Modelling Domestic Behaviour in Recovery from Total Hip Replacement Surgery," J. Healthc. Informatics Res., vol. 4, no. 3, pp. 238–260, Sep. 2020.
- [3] Masullo, Alessandro, et al. "No Need for a Lab: Towards Multi-sensory Fusion for Ambient Assisted Living in Real-world Living Homes." VISIGRAPP (5: VISAPP). 2021.



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